# **Vector**<sup>™</sup> H320<sup>™</sup> GNSS Compass Board

Advanced Heading & RTK Positioning

- Extremely accurate heading with short baselines
  - L1/L2 GPS/GLONASS RTK capable
  - L-Band DGNSS/HP/XP (OmniSTAR<sup>®</sup>) capable
  - Excellent coasting performance
- Fast RTK acquisition and reacquisition times
- 5 cm rms RTK-enabled heave accuracy
- Strong multipath mitigation and interference rejection



Develop sophisticated machine control and navigation solutions in a world full of complex dynamic environments. The Vector<sup>™</sup> H320<sup>™</sup> is our most advanced GNSS heading and positioning module available from Hemisphere GNSS.

The Vector H320 utilizes dual antenna ports to create a series of additional capabilities to Eclipse<sup>™</sup> Vector technology including fast, high-accuracy heading over short baselines, RTK positioning, on-board L-Band DGNSS/ HP/XP reception, RTK-enabled heave, low power consumption, and precise timing.

Integrate the Vector H320 into your applications to experience exceptional performance, flexibility and cost savings. This incredible GNSS module uses advanced multipath mitigation techniques and offers full scalability and expandability from L1/L2 GPS/GLONASS to L1/L2 GPS/GLONASS RTK performance.



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key features

# Vector H320 GNSS Compass Board

#### **GPS Sensor Specifications** Dual GNSS RTK

ReceiverType: Signals Received: Channels: GPS Sensitivity: SBAS Tracking: Update Rate: Horizontal Accuracy: RTK: 2 L-band DGNSS/HP/XP (OmniSTAR): 3 SBAS (WAAS): 3 Autonomous, no SA: 3 Heading Accuracy:

Rate of Turn:

Cold Start:

Hot Start:

Warm Start:

Heading Fix:

10 Hz standard, 20 Hz optional RMS (67%) 2DRMS (95%) 10 mm + 1 ppm 20 mm + 2 ppm 0.08 m 0.16 m 0.25 m 0.50 m 2.50 m 1.20 m < 0.17° rms @ 0.5 m antenna separation < 0.09° rms @ 1.0 m antenna separation < 0.04° rms @ 2.0 m antenna separation < 0.02° rms @ 5.0 m antenna separation Pitch / Roll Accuracy:  $< 1^{\circ} rms$ 30 cm rms (DGPS)<sup>4</sup>, 5 cm rms (RTK)<sup>4</sup> Heave Accuracy: Timing (1PPS) Accuracy: 20 ns 100°/s maximum < 40 s typical (no almanac or RTC) < 20 s typical (almanac and RTC) < 5 s typical (almanac, RTC and position) < 10 s typical (Hot Start) Antenna Input Impedance: 50 Ω 1,850 kph (999 kts) Maximum Speed: 18,288 m (60,000 ft) Maximum Altitude:

270

-142 dBm

GPS, GLONASS, and GALILEO<sup>1</sup>

3-channel, parallel tracking

### L-band DGNSS/HP/XP Sensor Specifications

-130 dBm Sensitivity: Channel Spacing: 7.5 kHz Satellite Selection: Manual and Automatic ReacquisitionTime: 15 seconds (typical) Rejection: 15 kHz spacing > 30 dB, 300 kHz spacing > 60 dB DSP for demodulation and protocol Processor: decoding module provides processing for the differential algorithms Command Support: Reports L-band DGNSS/HP/XP (OmniSTAR) region, satellite info, allows input and status of L-band DGNSS/HP/XP (OmniSTAR

#### Communications Serial Ports:

**Baud Rates:** Correction I/O Protocol:

Data I/O Protocol:

1 differential-only port), 1 USB Host, 1 USB Device 4800 - 115200 RTCM SC-104, L-Dif<sup>™</sup>, RTCM v2.3 (DGPS), RTCM v3 (RTK), CMR, CMR+ NMEA 0183, Crescent binary 5, L-Dif

4 full-duplex 3.3 V CMOS (3 main serial ports,

subscription, Bit Error Rate output for reception quality indication and manual frequency tuning

<sup>1</sup> Firmware update required <sup>2</sup> Depends on multipath environment, antenna selection, number of satellites in view, satellite geometry, baseline length (for local services), and ionospheric activity <sup>3</sup> Depends on multipath environment, number of satellites in view, satellite geometry, and ionospheric activity

<sup>4</sup> Based on a 40 second time constant <sup>5</sup> Hemisphere GPS proprietary

<sup>6</sup> Under static conditions

### Authorized Distributor:



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Rev. 04/14

#### Timing Output:

**Event Marker Input:** 

## Heading Warning I/O:

Power Input Voltage: Power Consumption: **Current Consumption:** Power Consumption:

**Current Consumption:** L-band Antenna Voltage: Antenna Short Circuit Protection: Antenna Gain Input Range: 10 to 40 dB Antenna Input Impedance: 50 Ω

#### Environmental

**Operating Temperature:** Storage Temperature: Humidity:

#### Mechanical

Dimensions:

Weight: Status Indication (LED):

Power/Data Connector: Antenna Connectors

#### **Aiding Devices** Gyro:

Tilt Sensors:

1PPS, CMOS, active low, falling edge sync, 10 kQ, 10 nE load CMOS, active low, falling edge sync, 10 k $\Omega$ , 10 pF load

- 3.3 VDC +/- 5% < 3.2 W at 3.3 V (L1/L2 GPS/GLONASS) < 970 mA at 3.3 V (L1/L2 GPS/GLONASS)
- < 3.9W at 3.3V (L1/L2 GPS/GLONASS; L-band DGNSS/HP/XP)
- < 1180 mA at 3.3V (L1/L2 GPS/GLONASS; DGNSS/HP/XP) 15 VDC maximum

Yes

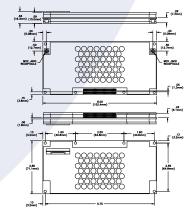
Pin 62

-40°C to +85°C (-40°F to +185°F) -40°C to +85°C (-40°F to +185°F) 95% non-condensing (when installed in an enclosure)

15.2 L x 7.1 W x 1.6 H (cm) 6.0 L x 2.8 W x 0.63 H (in) .105 kg (3.70 oz.) Power, Primary and Secondary GPS lock, Differential lock, DGPS position, Heading, RTK lock, L-band DGNSS/HP/XP lock 70-pin male header, 0.05" pitch (1.27 mm) MCX, female, straight

Provides smooth heading, fast heading reacquisition and reliable < 0.5° per min heading for periods up to 3 min. when loss of GPS has occurred 6

Provide pitch, roll data and assist in fast start-up and reacquisition of heading solution



# **Hemisphere**

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